HI-4853, 4854, 4855

High-Speed 3.0V to 5.5V, Slew-Rate Controlled RS-485/422 Transceivers with Extended Common-Mode Range

April 2019

GENERAL DESCRIPTION

The HI-485x devices are high-speed slew-rated controlled TIA-485/TIA-422-B and ISO 8482:1993 compliant transceivers with extended receiver common-mode range for avionic and industrial control applications. The devices can operate over an extended supply (3.0V to 5.5V) and temperature (-55°C to 125°C) range. The receiver input common-mode range of [-15, 20]V and ±24V for the half and full duplex configurations respectively, is valid over the full supply and temperature specification. The HI-4853 has a half-duplex configuration, and the HI-4854 and HI-4855 are full-duplex. Slew rates are optimized for data rates below 25Mbps. The drivers slew-rate control and pre-emphasis reduces high-frequency components in the output signal transitions and also compensates for impedance mismatch. These features provide optimum EMI and jitter performance, essential in EMI sensitive environments and high-integrity data link applications such as in aerospace and industrial controls.

The devices deliver at least ± 1.50V (VDD=3.0V), and ± 2.45V (VDD= 4.5V) output levels at an extended temperature range of -55°C to +125°C into a differential load of 54Ω and 50pF.

The receiver offers true Fail-Safe operation, providing a guaranteed logic high on RO when the bus is open-circuit, short-circuit, or idle (terminated but not driven). The receiver's worst case minimum input resistance is at least 90KΩ, supporting up to 224 nodes.

APPLICATIONS

• Extended Temperature Range RS-485/422 Networks
• Process Control and Factory Automation
• EMI Emission Sensitive Avionics
• Industrial Field Bus Networks
• Networks requiring extended common-mode range
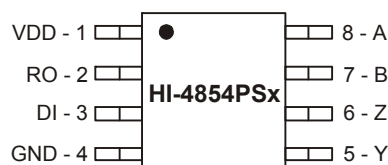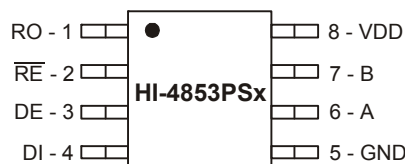• Miniature Munitions Stores Interface (MMSI / EBR-1553)

Device Selection Table			
Part Number	Half/Full Duplex	Data Rate (Mbps)*	Package
HI-4853	Half	≤ 20.0	8-pin SOIC
HI-4854	Full	≤ 20.0	8-pin SOIC
HI-4855	Full	≤ 20.0	14-pin SOIC 16-pin QFN

* For RS-485 Transceivers optimized for data rates up to 5Mbps please refer to the HI-4850 data sheet.
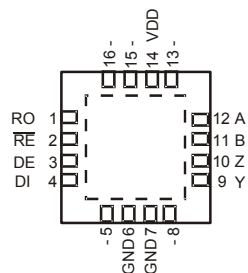
FEATURES

• Slew Rate Control and Pre-Emphasis for superior EMI
• Extended Power Supply Operating Range 3.0V to 5.5V
• Extended Receiver Common-Mode Range:
    • **-15.0V to 20.0V Half-Duplex**
    • **±24V Full-Duplex**
• ESD Protection
    • ±16KV HBM (Bus Pins)
    • ±8KV HBM (Logic Pins)
• 20 Mbps Data Rate up to 100 ft.   CAT-5 UTP
• 12 Mbps Data Rate up to 1000 ft. CAT-5 UTP
• Current Limiting Protection
• Extended Temperature Range -55°C to 125°C
• Industry Standard 75176 Pin-out

PIN CONFIGURATIONS (Top Views)

RO - 1 ● 8 - VDD
RE - 2 7 - B
DE - 3 **HI-4853PSx** 6 - A
DI - 4 5 - GND

VDD - 1 ● 8 - A
RO - 2 7 - B
DI - 3 **HI-4854PSx** 6 - Z
GND - 4 5 - Y

8-Pin Plastic SOIC package (Narrow Body)

16 - 15 - 14 VDD 13 -
RO 1 12 A
RE 2 11 B
DE 3 10 Z
DI 4 9 Y
5 - GND 6 GND 7 8 -

HI-4855PCx
16- pin 4mm x 4mm QFN

- 1 ● 14 VDD
RO 2 13 -
RE 3 12 A
DE 4 **HI-4855PSx** 11 B
DI 5 10 Z
GND 6 9 Y
GND 7 8 -
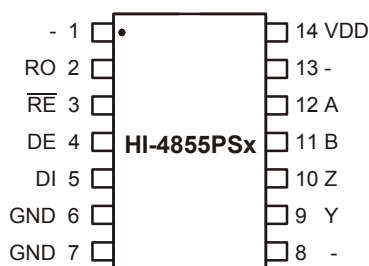
14-Pin Plastic SOIC package (Narrow Body)

PIN DESCRIPTIONS

SIGNAL	FUNCTION	DESCRIPTION
RO	OUTPUT	Receiver Output. If $V_{ID} \geq$ -50mV, then RO is high. If $V_{ID} <$ -150mV then RO is low. If the bus is shorted, open or terminated but not driven by another terminal, RO will be high.
$\overline{RE}$	INPUT	Receiver Enable. $\overline{RE}$= Low enables the receiver. $\overline{RE}$ High forces the receiver output (RO) into a high impedance state. Internal 450KΩ pull-down resistor
DE	INPUT	Driver Enable. DE = high enables the driver. DE = low will force the driver output into a high impedance state and the device will function as a line receiver if $\overline{RE}$ is also low. Internal 450KΩ pull-up resistor
DI	INPUT	Driver Input. Forces the logic state of the Driver's output, if Driver is enabled. Internal 450KΩ pull-up resistor
GND	POWER	Chip ground, 0V Supply
A, Y	ANALOG I/O	Non-inverting Receiver Input / Driver Output.
B, Z	ANALOG I/O	Inverting Receiver Input / Driver Output.
VDD	POWER	Positive Supply: 3.0V ≤ VDD ≤ 5.5V

TX FUNCTION TABLE

TRANSMITTING					
INPUTS			LINE CONDITION	OUTPUTS	
$\overline{RE}$	DE	DI		B	A
X	1	1	Transmit logic high	0	1
X	1	0	Transmit logic low	1	0
0	0	X	Disable	Hi-Z	Hi-Z
1	0	X	Shutdown	Hi-Z	Hi-Z

RX FUNCTION TABLE

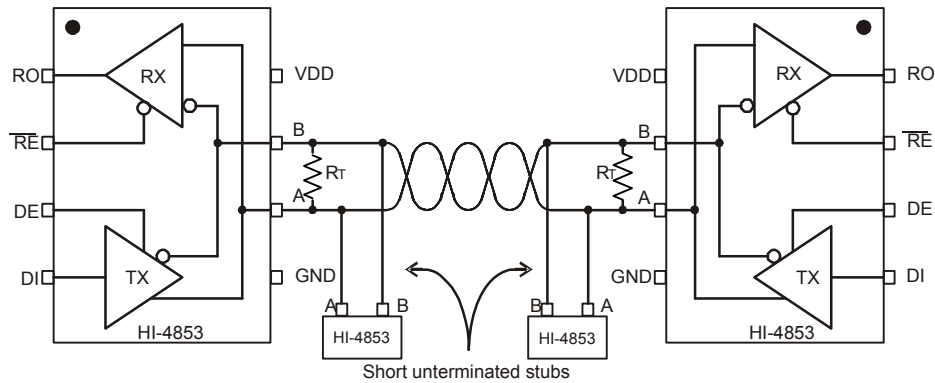| RECEIVING				
INPUTS		BUS PINS $V_{ID} = V_A - V_B$	OUTPUT RO	OPERATION
$\overline{RE}$	DE			
0	0	-150mV < V_{ID} < -50mV	X	Undefined Input
0	X	-50mV ≤ V_{ID}	1	Receiver logic high
0	X	V_{ID} ≤ -150mV	0	Receiver logic low
0	0	Open or Shorted	1	Default
0	0	Idle and terminated	1	Default
1	1	X	Hi-Z	Disabled
1	0	X	Hi-Z	Shutdown

Typical Operating Circuit

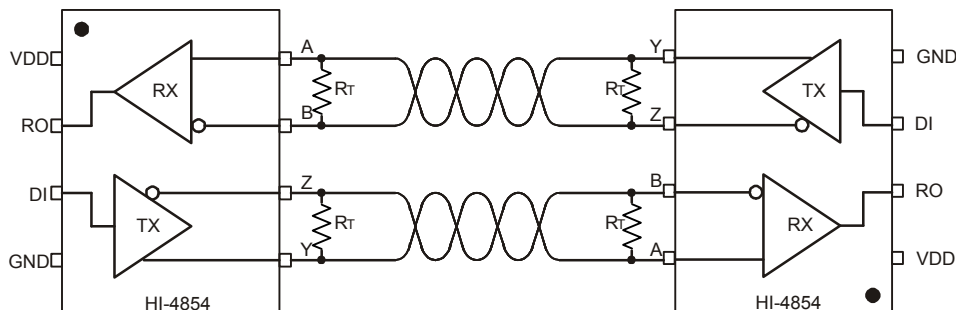**Figure 1 - Typical half-duplex configuration**

Figure 2 - Typical full-duplex 8-pin configuration

ABSOLUTE MAXIMUM RATINGS
(Voltages referenced to GND = 0V)

Supply Voltage, VDD:..7 V	Operating Temperature Range:(Industrial)........................-40°C to +85°C
Control Input Currents: ....-100mA to 100mA	(Hi-Temp).......................-55°C to +125°C
Digital Input Voltages (DI, DE, $\overline{RE}$): ....-0.5V to VDD + 0.5V	
Bus Voltage (AY, BZ): .... ±25V	
Digital Output Voltage (RO):...-0.5V to V + 0.5V	Internal Power Dissipation:...900mW
Short-Circuit Duration, Driver (V: ±15V)..∞	Storage Temperature Range: ....-65°C to +150°C
ESD (Human Body Model):	
AY, BZ,VDD,GND pins:...±16KV	Solder Temperature: (Reflow)...260°C
DI, DE, $\overline{RE}$, RO pins:..±8KV	

NOTE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

SPECIFIED OPERATING CONDITIONS

PARAMETERS	SYMBOL	CONDITIONS	LIMITS			UNIT
			MIN	TYP	MAX	
Supply Voltage	V_{DD}		3.0	3.3 / 5.0	5.5	V
Temperature	T		-55		125	°C
TX Common-Mode Bus Loading	V_{OCM}	See Figure 4	-7		12	V
RX Input Common-Mode Voltage	V_{ICM}	Half-Duplex	-16		20	V
Differential Load Resistance	R_L		54	60	∞	Ω
Differential Load Capacitance	C_L			100		pF
Digital Input High Voltage	V_{IH}	DE, DI, $\overline{RE}$	70			%V_{DD}
Digital Input Low Voltage	V_{IL}	DE, DI, $\overline{RE}$			30	%V_{DD}
Digital Input Current high	I_{IH}	DE, DI, $V_{IH} = V_{DD}$			1	µA
Digital Input Pull-Down Current	I_{PD}	$\overline{RE}$, $V_{IH} = V_{DD}$	6		18	µA
Digital Input Current low	I_{IL}	$\overline{RE}$, $V_{IH} = 0$	-1			µA
Digital Input Pull-Up Current	I_{PU}	DE, DI, $V_{IH} = 0V$	-18		-6	µA

# DRIVER DC ELECTRICAL CHARACTERISTICS
VDD = 3.0V to 3.6V or 4.5V to 5.5V; T = -55°C to 125°C; MIN and MAX values are at range boundaries

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Differential Output Voltage with no load	$\|V_{OD1}\|$	$R_L = ∞$	3	V_{DD} -0.1		V_{DD}	V_{DD} -0.1		V_{DD}	V
Differential Output Voltage into load with no common-mode voltage	$\|V_{OD2}\|$	$R_L = 54Ω$, $C_L = 50pF$	3	1.5		3.0	2.45		4.0	V
Differential Output Voltage into load with applied common-mode voltage	$\|V_{OD3}\|$	$-7V ≤ V_{OCM} ≤ 12V$ $T_A = 25°C$	4	1.5		3.0	2.45		4.0	V
Differential Output Over/Under Shoot						5.5			3.2	%V_{OD}
Change in Differential Output Voltage between logic states	ΔV_{OD}	$R_L = 54Ω$, $C_L = 50pF$	3	-125		125	-125		125	mV
Output Common-Mode Voltage	V_{OCM}	$R_L = 54Ω$, $C_L = 50pF$	4	1.40	1.60	2.0	2.15	2.45	3.0	V
Change in output Common-Mode Voltage between logic states	ΔV_{OCM}	$R_L = 54Ω$, $C_L = 50pF$	4	-125		125	-150		150	mV
Bus Pin Leakage Current (High-Z Power On)	I_{OHZ1}	DE=0, $-15V ≤ VOCM ≤ 15V$ DE=0, $-12V ≤ VOCM ≤ 15V$		-200		200	-200		200	µA
Bus Pin Leakage Current (Power Off)	I_{OHZ2}	$V_{OCM} = ±15V$		-200		200	-200		200	µA
Peak Short Circuit Current	I_{SCPK}	DE = V_{DD}, Bus Pin = ±15		-230		230	-250		250	mA
Steady State Short Circuit Current	I_{SC}	DE = V_{DD}, Bus Pin = ±15		0		50	0		50	µA
Differential Output Capacitance	C_{OD}	DE = 0				16			16	pF
Static Supply Current	I_{DD}	DE=V_{DD}, RE=0, $R_L=∞$			8	10		10	12	mA
Supply Current (Shutdown)	I_{DDQ}	DE=0, RE=V_{DD}, $R_L=∞$			90	110		125	400	µA

DRIVER SWITCHING CHARACTERISTICS

VDD = 3.0V - 3.6V or 4.5V - 5.5V as noted , Operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Propagation Delay Low - to - High	t_{PDR}	$R_L = 54_Z$. $C_L = 50pF$	5 & 6	17	26	33	16	24	30	ns
Propagation Delay High - to - Low	t_{PDF}	$R_L = 54_Z$, $C_L = 50pF$	5 & 6	17	26	33	16	24	30	ns
Differential Rise Time	t_r	$R_L = 54_Z$, $C_L = 50pF$	5 & 6	9	12	15	8	11	16	ns
Differential Fall Time	t_f	$R_L = 54_Z$, $C_L = 50pF$	5 & 6	9	12	15	8	11	16	ns
Output Pulse Skew	t_{MSK}	$R_L = 54_Z$, $C_L = 50pF$	5 & 6		2	8		2	8	ns
Driver Enable to Output High	t_{ZH}	$R_L = 500_Z$, $C_L = 50pF$	7		95	120		90	117	ns
Driver Enable to output Low	t_{ZL}	$R_L = 500_Z$, $C_L = 50pF$	7		95	120		90	117	ns
Driver Disable from Output High	t_{HZ}	$R_L = 500_Z$, $C_L = 50pF$	7		20	33		18	30	ns
Driver Disable from Output Low	t_{LZ}	$R_L = 500_Z$, $C_L = 50pF$	7		20	33		18	30	ns
Shutdown to Active Output Delay	t_{ON}	$R_L = 500_Z$, $C_L = 50pF$	7			10			10	µs
Shutdown Delay	t_{OFF}					10			10	µs

RECEIVER DC ELECTRICAL CHARACTERISTICS

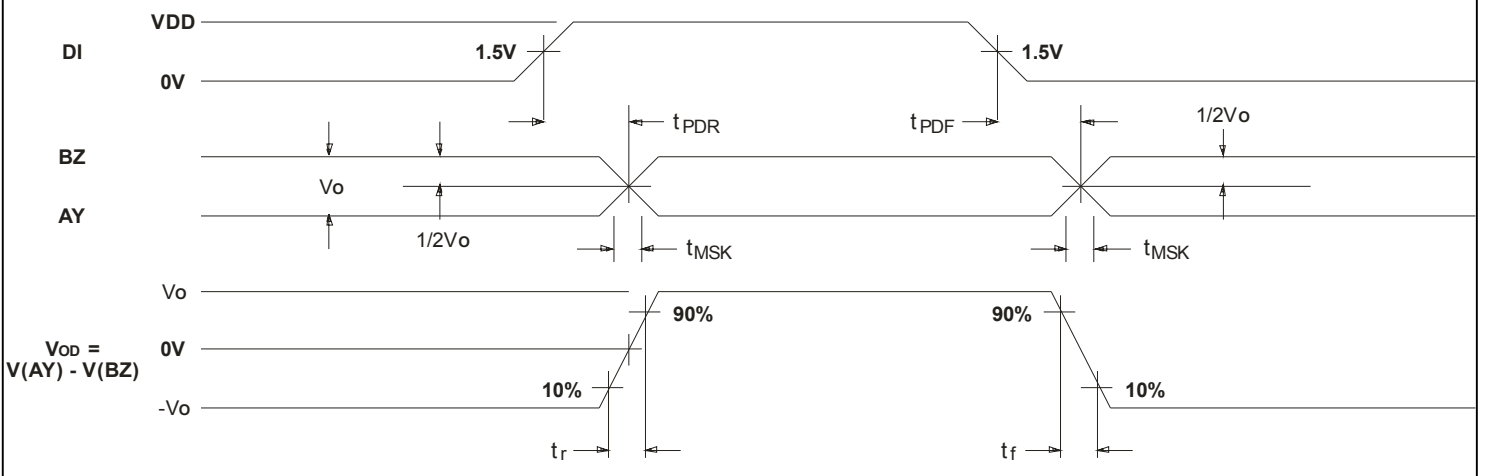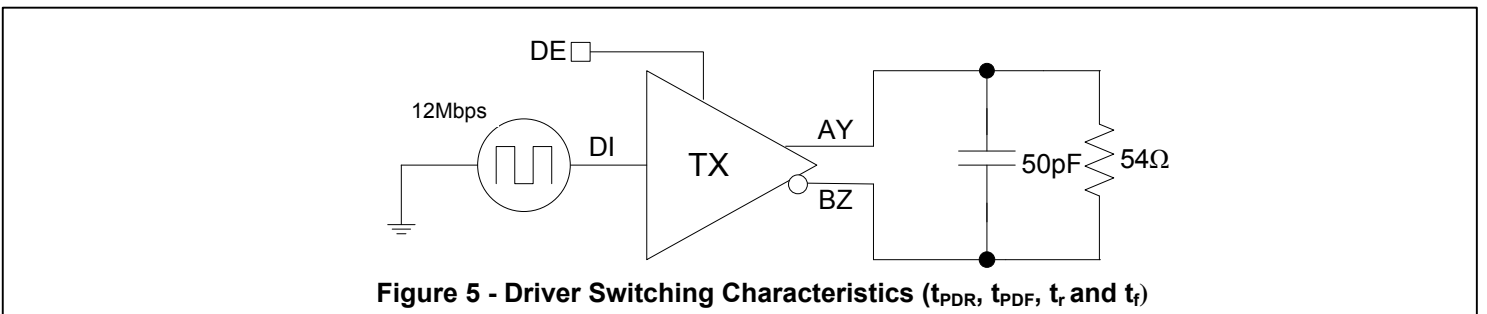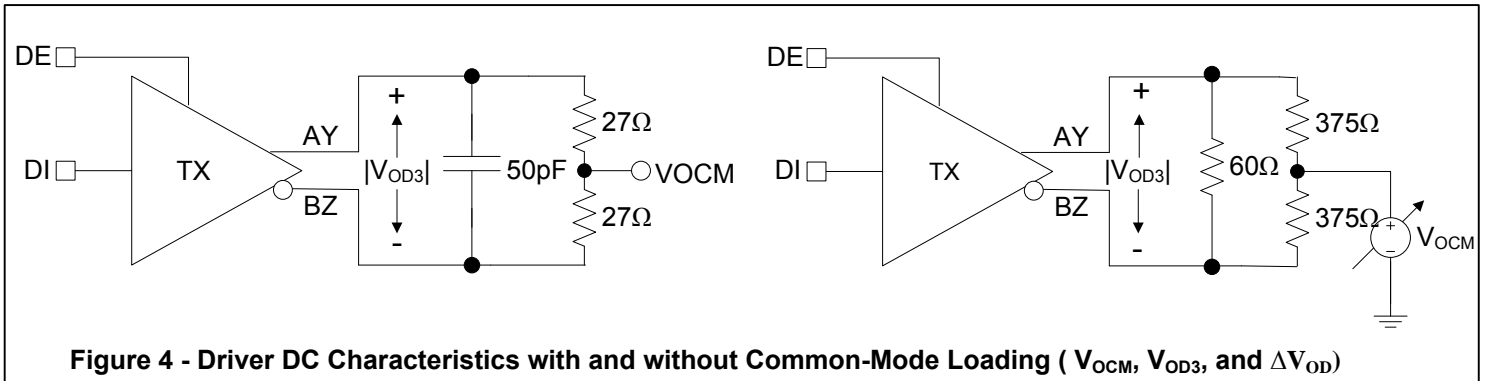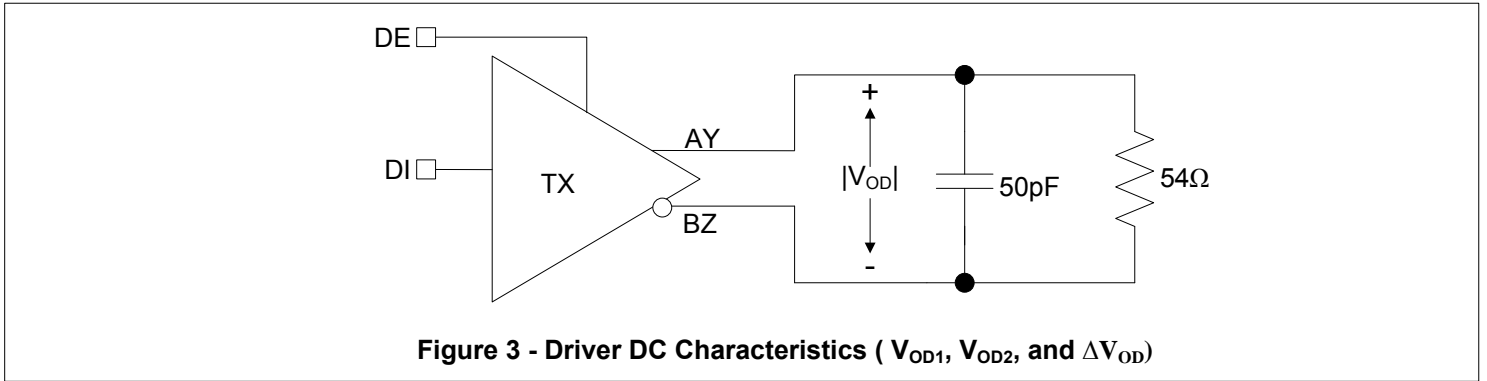VDD = 3.0V - 3.6V or 4.5V - 5.5V as noted , Operating temperature range.

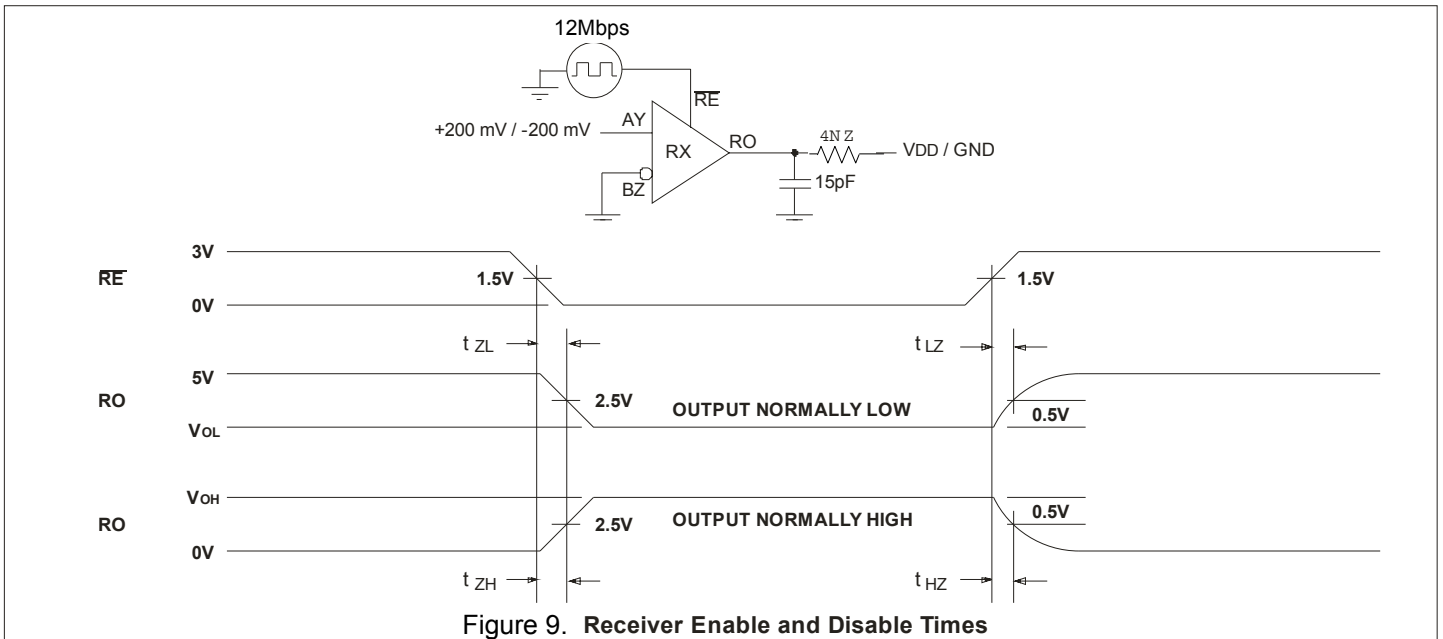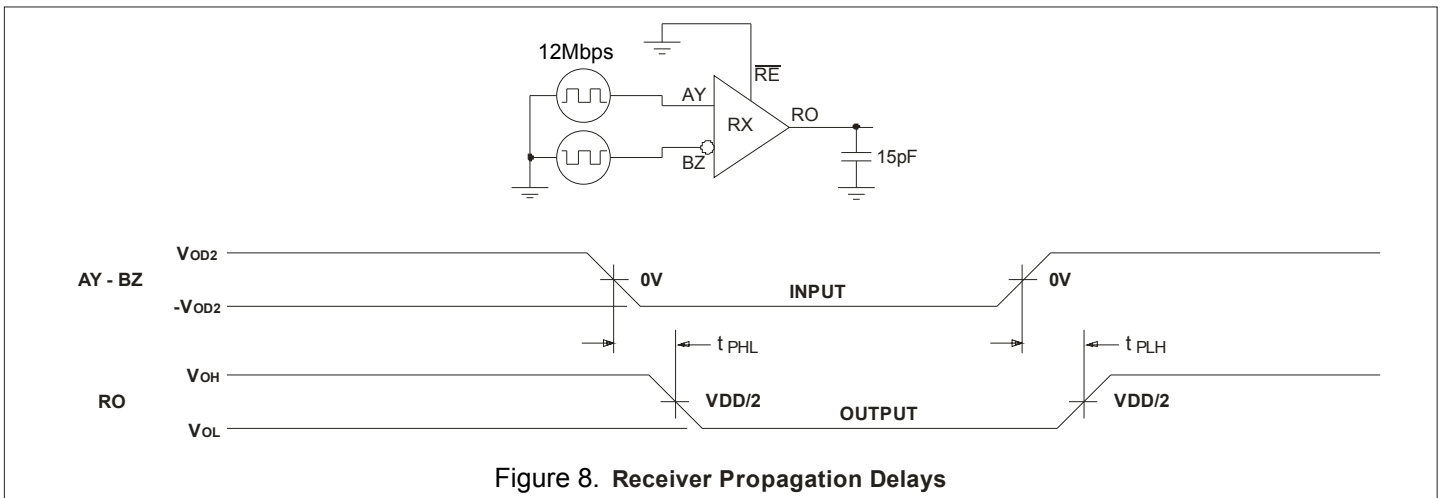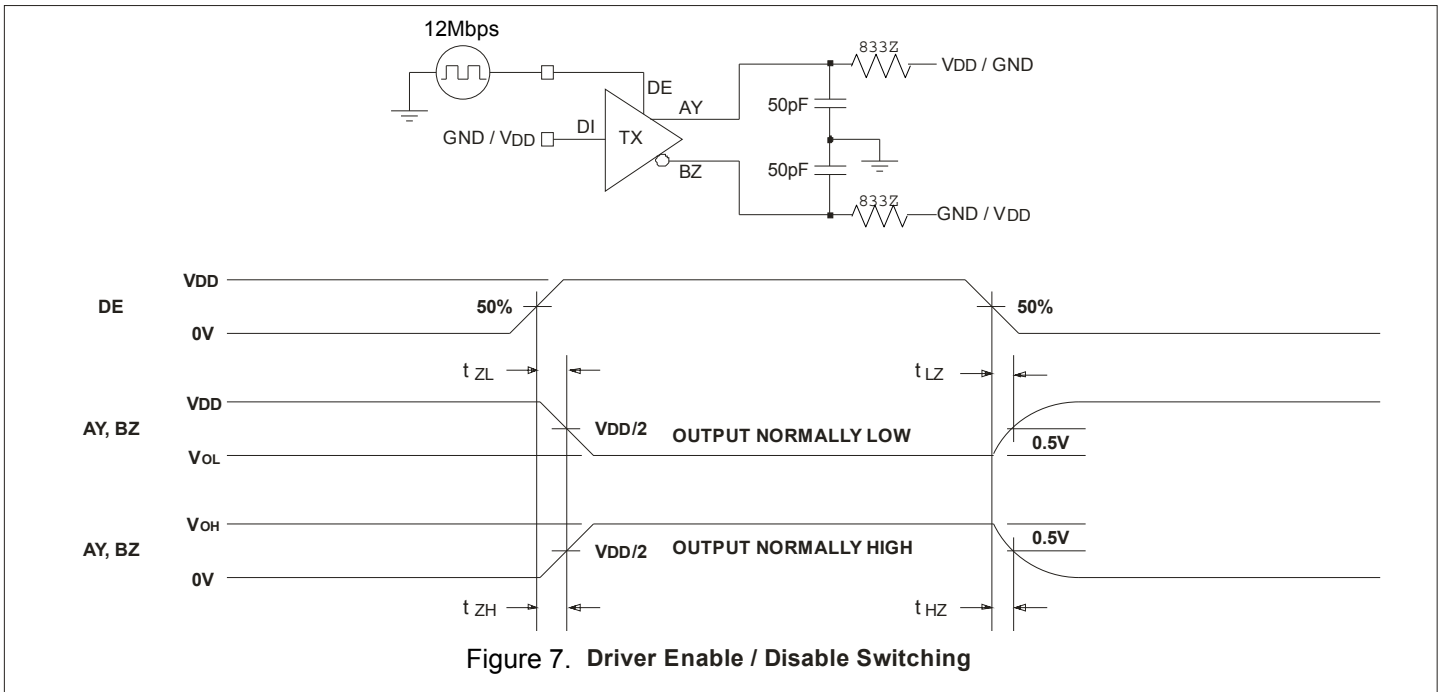| PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Differential Input Threshold Voltage	V_{TH}	$-15 \le V_{ICM} \le +20$		-200	-100	-50	-200	-100	-50	mV mV
Input Hysteresis	V_{HYS}	$V_{ICM} = 0V$		17	28	33	17	28	33	mV
Input Resistance	R_{IN}	$-15 \le V_{ICM} \le +20$		80	92		80	92		K_Z K_Z
RO Output High Level	V_{OH}	$V_{ICM} = +200mV$ $I_{OUT} = -3.0mA$		90%			90%			V_{DD}
RO Output Low Level	V_{OL}	$V_{ICM} = -200mV$ $I_{OUT} = +3.0mA$				10%			10%	V_{DD}
RO Output Hi-Z Leakage Current	I_{OZH}	$0V \le V_{RO} \le V_{DD}$		-1		1	-1		1	µA

RECEIVER SWITCHING CHARACTERISTICS

VDD = 3.0V - 3.6V or 4.5V - 5.5V as noted , Operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Propagation Delay Low - to - High	t_{RPDR}	$V_{ID} = +1.5V$, $C_L = 15pF$	8	20	26	32	20	26	32	ns
Propagation Delay High - to - Low	t_{RPDF}	$V_{ID} = -1.5V$, $C_L = 15pF$	8	20	26	32	20	26	32	ns
RO Output Rise Time	t_{Rr}	$V_{ID} = +1.5V$, $C_L = 15pF$	8	1.1	1.9	3.3	1.1	1.9	3.3	ns
RO Output Fall Time	t_{Rf}	$V_{ID} = -1.5V$, $C_L = 15pF$	8	1.1	1.9	3.3	1.1	1.9	3.3	ns
Output Pulse Skew	t_{RMSK}	$V_{ID} = +1.5V$, $C_L = 15pF$	8		0.8	1.6		0.8	1.6	ns
Receiver Enable to RO Output High	t_{RZH}	$R_L = 1K_Z$, $C_L = 15pF$	9		12	16		12	16	ns
Receiver Enable to output Low	t_{RZL}	$R_L = 1K_Z$, $C_L = 15pF$	9		12	16		12	16	ns
Receiver Disable from Output High	t_{RHZ}	$R_L = 1K_Z$, $C_L = 15pF$	9		6	10		6	10	ns
Receiver Disable from Output Low	t_{RLZ}	$R_L = 1K_Z$, $C_L = 15pF$	9		6	10		6	10	ns
Shutdown to RO Active Output Delay	t_{RON}	$R_L = 1K_Z$, $C_L = 15pF$	9			5			5	µs
Shutdown Delay to RO HiZ	t_{ROFF}	$R_L = 1K_Z$, $C_L = 15pF$	9		60	100		60	100	ns

TEST CIRCUITS

Figure 3 - Driver DC Characteristics (V_{OD1}, V_{OD2}, and ΔV_{OD})

Figure 4 - Driver DC Characteristics with and without Common-Mode Loading (V_{OCM}, V_{OD3}, and ΔV_{OD})

Figure 5 - Driver Switching Characteristics (t_{PDR}, t_{PDF}, t_r and t_f)

Figure 6. Driver Switching Waveforms

Figure 7. Driver Enable / Disable Switching

Figure 8. Receiver Propagation Delays

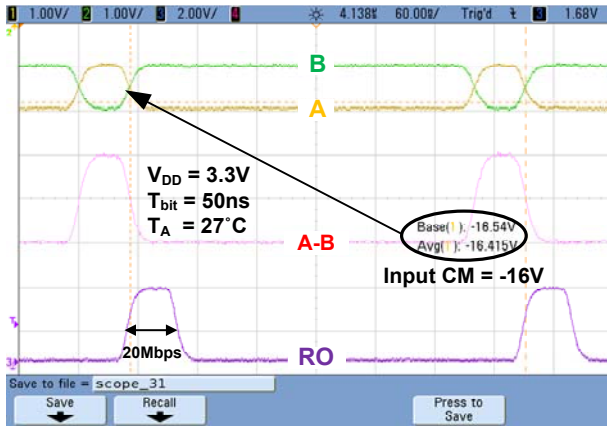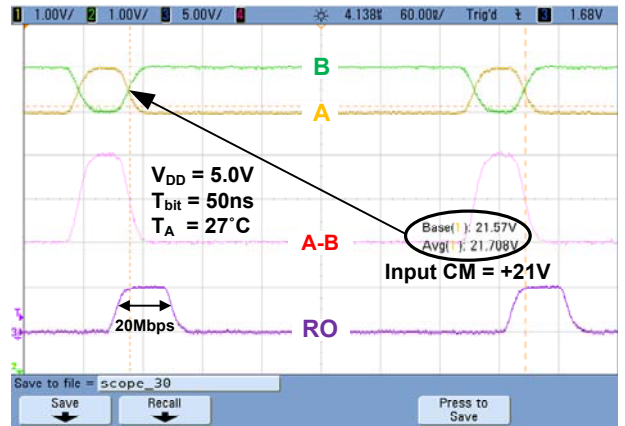Figure 9. Receiver Enable and Disable Times

EXTENED COMMON-MODE PERFORMANCE CHARACTERISITICS

RX Extended Common-Mode Range:
Typical Supply, Maximum (-) Common-Mode

V_{DD} = 3.3V
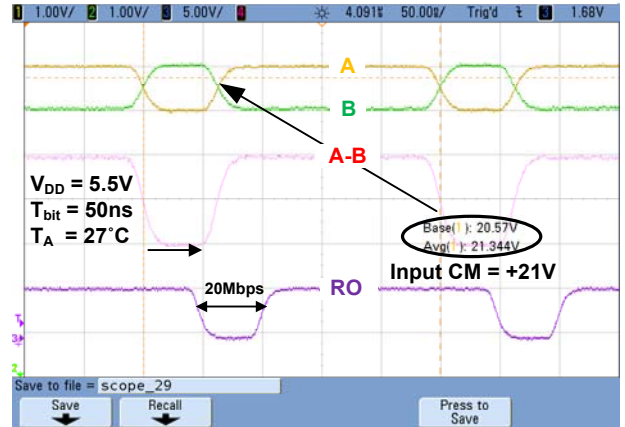T_{bit} = 50ns
T_A = 27˚C

Base(1): -16.54V
Avg(1): -16.415V

Input CM = -16V

20Mbps

RX Extended Common-Mode Range:
Typical Supply, Maximum (+) Common-Mode

V_{DD} = 5.0V
T_{bit} = 50ns
T_A = 27˚C

Base(1): 21.57V
Avg(1): 21.708V

Input CM = +21V

20Mbps

RX Extended Common-Mode Range:
Maximum Supply, Maximum (-) Common-Mode

V_{DD} = 5.5V
T_{bit} = 50ns
T_A = 27˚C

Measure	Current	Mean	Max	Std Dev	Count
Base(1):	-15.20V	-15.193V	-15.26V	-15.14V	12.906mV	1.463k
Avg(1):	-14.411V	-14.410V	-14.418V	-14.397V	2.4761mV	1.462k

Input CM = -15V

Base(1): -15.20V   Avg(1): -14.411V

RX Extended Common-Mode Range:
Maximum Supply, Maximum (+) Common-Mode

V_{DD} = 5.5V
T_{bit} = 50ns
T_A = 27˚C

Base(1): 20.57V
Avg(1): 21.344V

Input CM = +21V

20Mbps

RX Extended Common-Mode Range:
Minimum Supply, Maximum (-) Common-Mode

V_{DD} = 3.0V
T_{bit} = 100ns
T_A = 27˚C

Avg(1): -16.047V

Input CM = -16V

RX Extended Common-Mode Range:
Minimum Supply, Maximum (+) Common-Mode

V_{DD} = 3.0V
T_{bit} = 100ns
T_A = 27˚C

Avg(1): 22.427V

Input CM = +22V
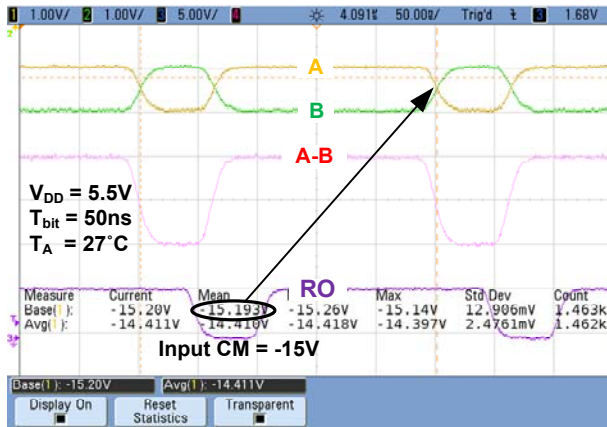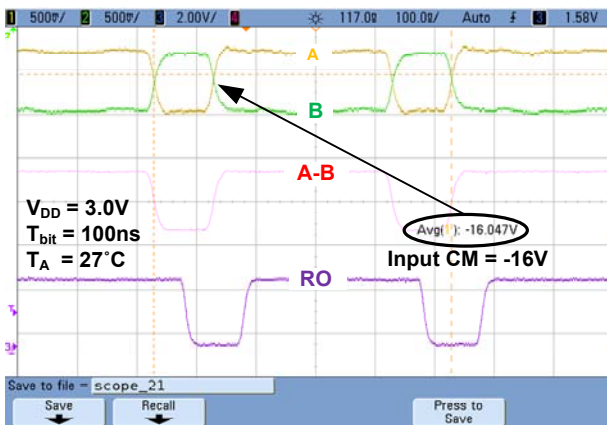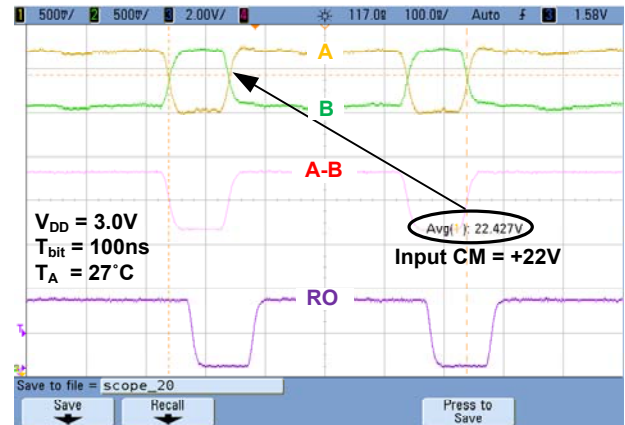
High-Speed Performance Characteristics Over Distance

10Mbps Data Pulse Over 1000ft 2 CAT-5 UTP

2V/DIV

DI$_{TX}$

B$_{TX}$

A$_{TX}$

V_{DD} = 3.0V
f_{data} = 10Mbps
T_A = 27°C

100ns/DIV

RO$_{RX}$

+Width(4): 99ns   +Width(3): 81ns

| Source 3 | Select: +Width | Measure +Width | Clear Meas | Settings | Thresholds |

12Mbps Data Pulse Over 1000ft 2 CAT-5 UTP

2V/DIV

DI$_{TX}$

B$_{TX}$

A$_{TX}$

100ns/DIV

V_{DD} = 3.0V
f_{data} = 12Mbps
T_A = 27°C

RO$_{RX}$

+Width(4): 80ns   +Width(3): 86ns

| Source 4 | Select: +Width | Measure +Width | Clear Meas | Settings | Thresholds |

20Mbps Data Pulse Over 1000ft 2 CAT-5 UTP

2V/DIV

DI$_{TX}$

B$_{TX}$

A$_{TX}$

V_{DD} = 3.0V
f_{data} = 20Mbps
T_A = 27°C

100ns/DIV

RO$_{RX}$

+Width(4): 49ns   +Width(3): 44ns

| Source 3 | Select: +Width | Measure +Width | Clear Meas | Settings | Thresholds |

20Mbps Data Over 250ft CAT-5 UTP

2V/DIV

B$_{TX}$

A$_{TX}$

V_{DD} = 3.0V
f_{data} = 20Mbps
T_A = 27°C

50ns/DIV

RO$_{RX}$

Measure	Current	Mean	Min	Max	Std Dev	Count
+Width(4)	49.5ns	50.628ns	49.0ns	52.0ns	613.97ps	13.54k
+Width(3)	54.0ns	51.5ns	56.2ns	573.17ps	13.56k	

+Width(4): 49.5ns   +Width(3): 54.0ns

| Source 3 | Select: +Width | Measure +Width | Settings | Clear Meas | Statistics |

20Mbps Data Over 250ft CAT-5 UTP

DI$_{TX}$

2V/DIV

B$_{TX}$

A$_{TX}$

V_{DD} = 3.0V
f_{data} = 20Mbps
T_A = 27°C

50ns/DIV

RO$_{RX}$

Measure	Current	Mean	Min	Max	Std Dev	Count
-Width(4)	51.0ns	51.090ns	49.5ns	52.0ns	291.94ps	6.091k
-Width(3)	56.0ns	55.900ns	54.0ns	58.0ns	550.36ps	6.091k

-Width(4): 51.0ns   -Width(3): 56.0ns

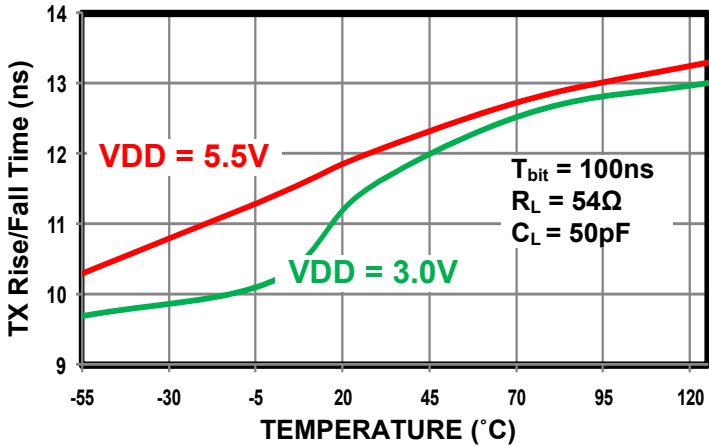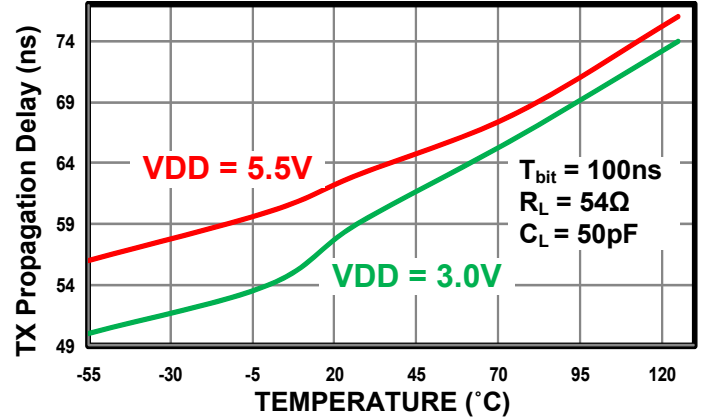| Display On | Reset Statistics | Transparent |

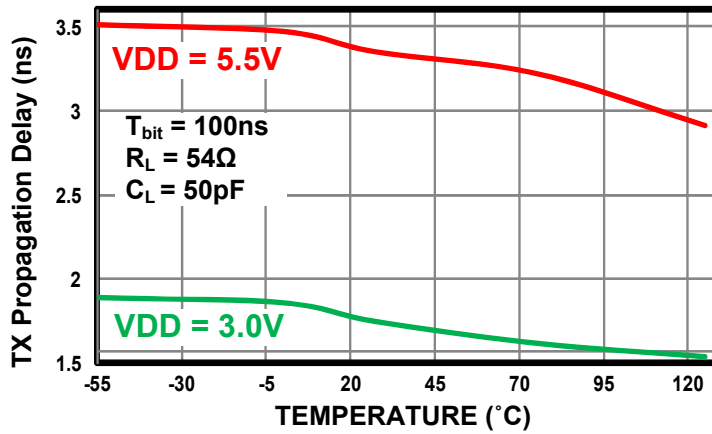# PERFORMANCE CHARACTERISTICS OVER SUPPLY AND TEMPERATURE

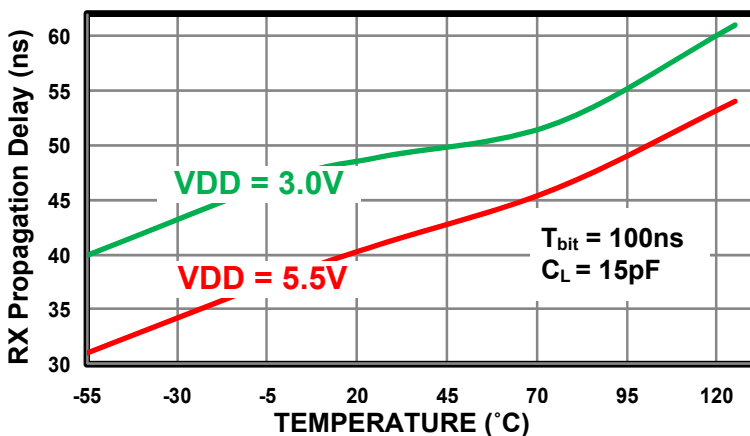## TX Differential Rise/Fall Time vs. Temperature
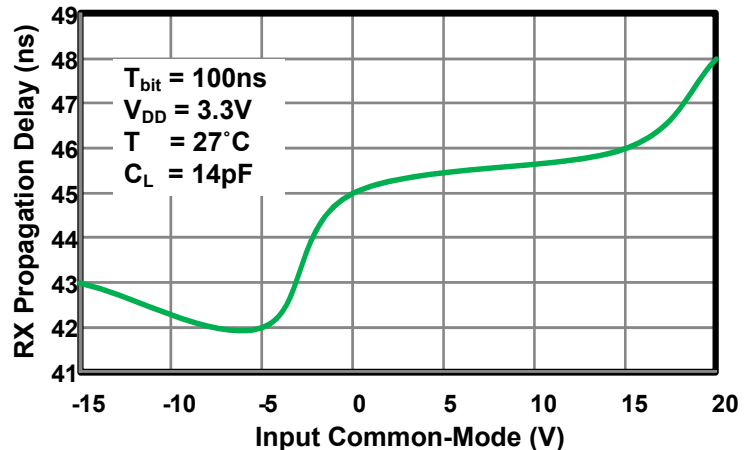

TX Differential Rise/Fall Time vs. Temperature

TX Differential Zero To Peak Amplitude

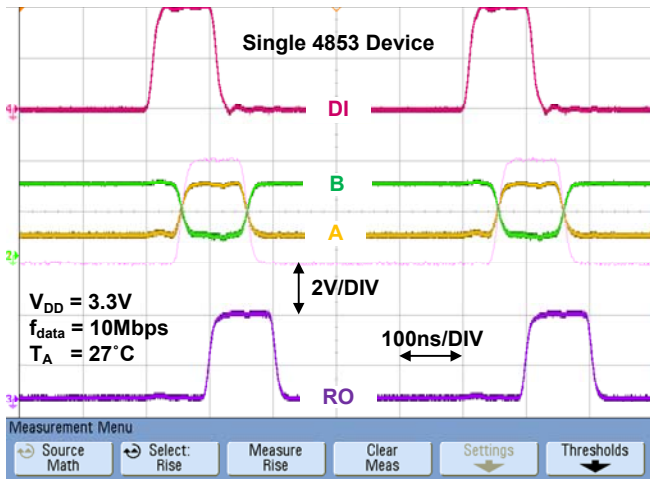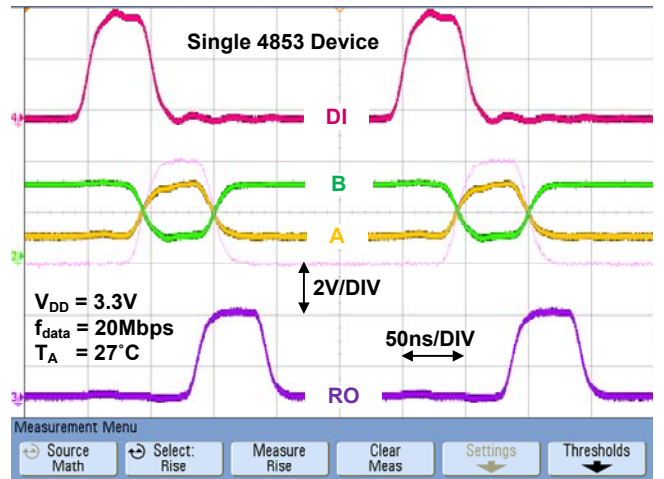## RX Propagation Delay vs. Temperature

RX Propagation Delay vs. Common-Mode
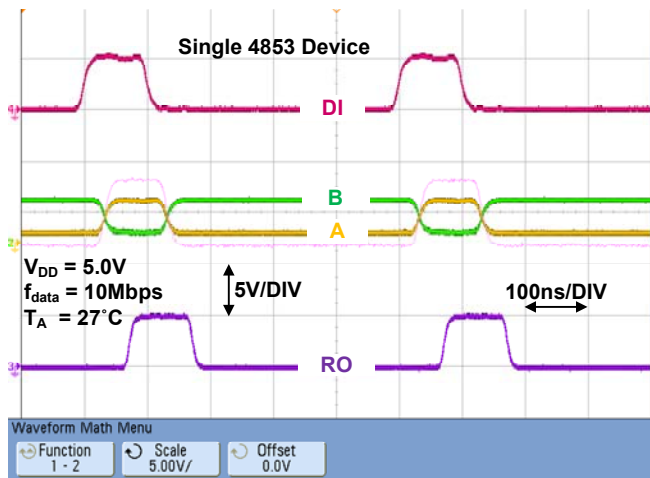
TYPICAL TRANSCEIVER PERFORMANCE CHARACTERISITICS

Typical 10Mb/s Operation: $R_L = 54\Omega$; $C_L = 50pF$

Single 4853 Device

DI

B

A

2V/DIV

$V_{DD} = 3.3V$
$f_{data} = 10Mbps$
$T_A = 27°C$

100ns/DIV

RO

Measurement Menu

| Source Math | Select: Rise | Measure Rise | Clear Meas | Settings | Thresholds |

Typical 20Mb/s Operation: $R_L = 54\Omega$; $C_L = 50pF$

Single 4853 Device

DI

B

A

2V/DIV

$V_{DD} = 3.3V$
$f_{data} = 20Mbps$
$T_A = 27°C$

50ns/DIV

RO

Measurement Menu

| Source Math | Select: Rise | Measure Rise | Clear Meas | Settings | Thresholds |

Typical 10Mb/s Operation: $R_L = 54\Omega$; $C_L = 50pF$

Single 4853 Device

DI

B

A

$V_{DD} = 5.0V$
$f_{data} = 10Mbps$
$T_A = 27°C$

5V/DIV

100ns/DIV

RO

Waveform Math Menu

| Function 1 - 2 | Scale 5.00V/ | Offset 0.0V |

Typical 20Mb/s Operation: $R_L = 54\Omega$; $C_L = 50pF$

Single 4853 Device

DI

B

A

$V_{DD} = 5.0V$
$f_{data} = 20Mbps$
$T_A = 27°C$

5V/DIV

50ns/DIV

RO

Waveform Math Menu

| Function 1 - 2 | Scale 5.00V/ | Offset 0.0V |

RX Output Jitter Over CM and Input Amplitude (5.5V)

Timing Jitter: 0.5UI = 50ns$_{PK-PK}$
Resulting in a 5% Duty Error

$V_{CM} = +20V$

$V_{CM} = 0V$

$V_{CM} = -15V$

RX Output Jitter (UI)

Input Signal Amplitude (V)

RX Output Jitter Over CM and Input Amplitude (3.0V)

Timing Jitter: 0.5UI = 50ns$_{PK-PK}$
Resulting in a 5% Duty Error

$V_{CM} = +20V$

$V_{CM} = 0V$

$V_{CM} = -15V$

RX Output Jitter (UI)

Input Signal Amplitude (V)

ORDERING INFORMATION

HI-485x xx x x

PART NUMBER	LEAD FINISH
Blank	Tin / Lead (Sn / Pb) Solder
F	100% Matte Tin (Pb-free, RoHS compliant)

PART NUMBER	TEMPERATURE RANGE	FLOW	BURN IN
I	-40°C TO +85°C	I	NO
T	-55°C TO +125°C	T	NO
M	-55°C TO +125°C	M	YES

PART NUMBER	PACKAGE DESCRIPTION
PS	8 PIN PLASTIC NARROW BODY SOIC (8HN) (HI-4853, HI-4854)
PS	14 PIN PLASTIC NARROW BODY SOIC (14HN) (HI-4855 only)
CR	8 PIN CERDIP (8D) not available Pb-free (HI-4853, HI-4854)

PART NUMBER	FUNCTION
4853	HALF DUPLEX TRANSCEIVER
4854	FULL DUPLEX TRANSCEIVER ALWAYS ENABLED
4855	FULL DUPLEX TRANSCEIVER WITH ENABLE PINS

ORDERING INFORMATION

HI-<u>4855</u> <u>xx</u> <u>x</u> <u>x</u>

PART NUMBER	LEAD FINISH		
Blank	NiPdAu		
F	NiPdAu (Pb-free, RoHS compliant)		

PART NUMBER	TEMPERATURE RANGE	FLOW	BURN IN
I	-40°C TO +85°C	I	NO
T	-55°C TO +125°C	T	NO

PART NUMBER	PACKAGE DESCRIPTION
PC	16 PIN PLASTIC 4 x 4 mm QFN (16PCS)

PART NUMBER	FUNCTION
4855	FULL DUPLEX TRANSCEIVER WITH ENABLE PINS

REVISION HISTORY

Revision	Date	Description of Change
DS4853, Rev New	03/30/2012	Initial Release
Rev. A	05/21/2012	Fix typos on package ordering information
Rev. B	08/2/2012	Updated Rx Function Table rows 2 and 3 on p. 2 for DE = X. Updated package drawings for SOIC-8 (8HN), QFN-16 (16PCS) and SOIC-14 (14HN) packages.
Rev. C	02/25/2013	Correct typo on nRE pull-up resistor (should be pull-down). Update Digital Input pull-up/pull-down current. Update typo in Figure 4 resistors. Update solder temperature (reflow) in Max. Ratings
Rev. D	04/24/2019	Correct typo in QFN package drawing. Remove redundant Control Input Voltages from Absolute Maximum Ratings (same parameter as Digital Input Voltages). Update QFN lead finish to NiPdAu.

HOLT
INC.
INTEGRATED CIRCUITS

8-PIN PLASTIC SMALL OUTLINE (SOIC) - NB
(Narrow Body)

inches (millimeters)

Package Type: 8HN

$\frac{.193}{(4.90)}$ BSC

$\frac{.007 \pm .003}{(.175 \pm .075)}$

$\frac{.236}{(6.00)}$ BSC

PIN 1

$\frac{.154}{(3.90)}$ BSC

See Detail A

$\frac{.016 \pm .004}{(.410 \pm .100)}$

$\frac{.056 \pm .006}{(1.413 \pm .163)}$

0· to 8·

$\frac{.007 \pm .003}{(.175 \pm .075)}$

$\frac{.033 \pm .017}{(.835 \pm .435)}$
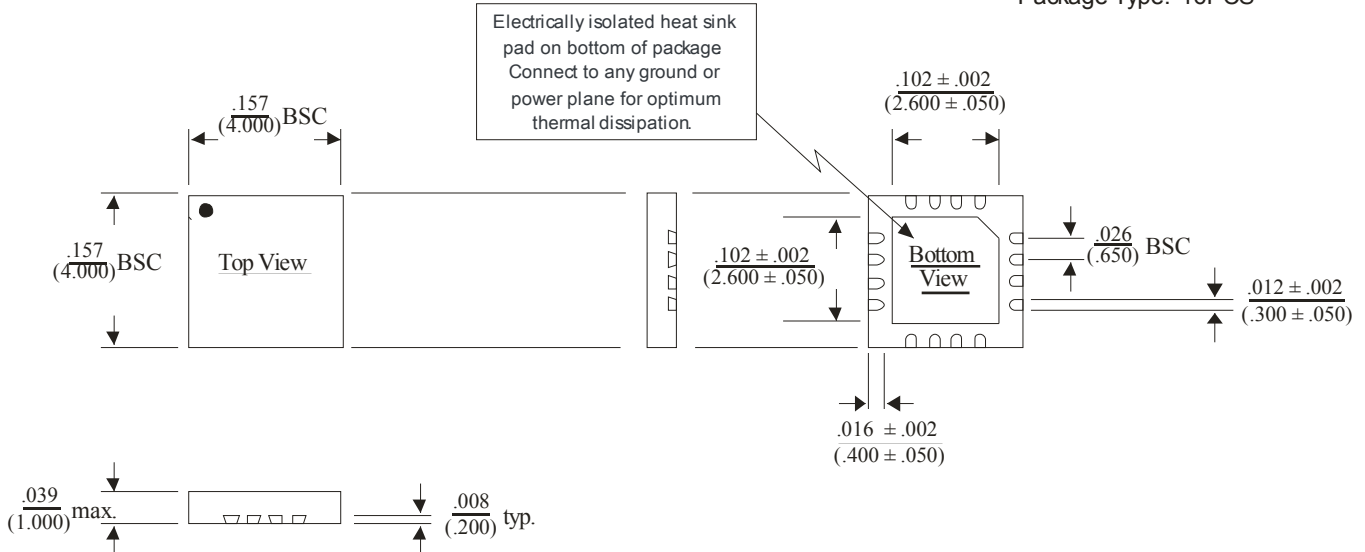
Detail A

$\frac{.050}{(1.27)}$ BSC
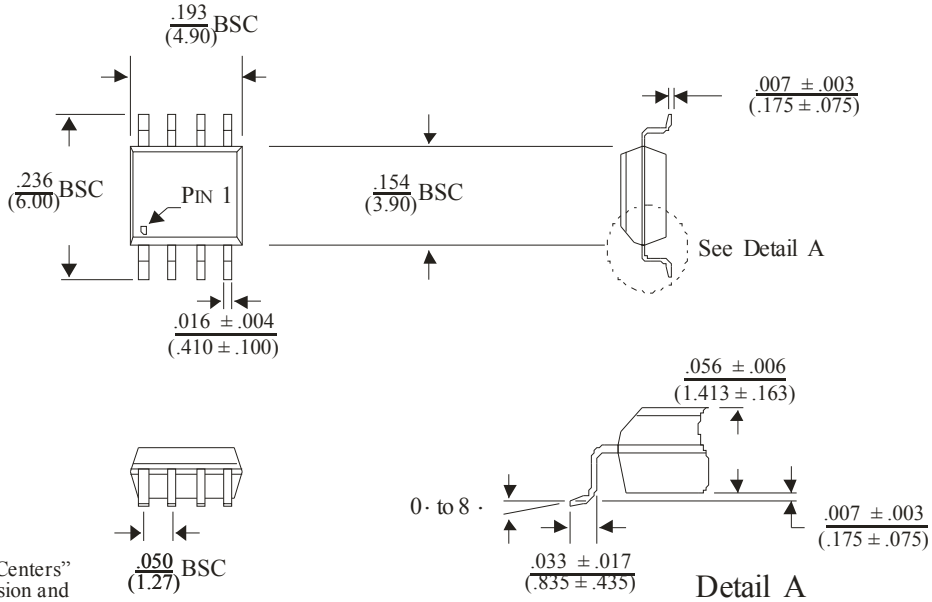
BSC = "Basic Spacing between Centers"
is theoretical true position dimension and
has no tolerance. (JEDEC Standard 95)

16-PIN PLASTIC CHIP-SCALE PACKAGE

inches (millimeters)

Package Type: 16PCS

Electrically isolated heat sink
pad on bottom of package
Connect to any ground or
power plane for optimum
thermal dissipation.

$\frac{.157}{(4.000)}$ BSC

$\frac{.102 \pm .002}{(2.600 \pm .050)}$

$\frac{.157}{(4.000)}$ BSC

Top View

$\frac{.102 \pm .002}{(2.600 \pm .050)}$

Bottom View

$\frac{.026}{(.650)}$ BSC

$\frac{.012 \pm .002}{(.300 \pm .050)}$

$\frac{.016 \pm .002}{(.400 \pm .050)}$

$\frac{.039}{(1.000)}$ max.

$\frac{.008}{(.200)}$ typ.

BSC = "Basic Spacing between Centers"
is theoretical true position dimension and
has no tolerance. (JEDEC Standard 95)

HOLT
INTEGRATED CIRCUITS

14-PIN PLASTIC SMALL OUTLINE (SOIC) - NB
(Narrow Body)

inches (millimeters)

Package Type: 14HN

$\frac{.341}{(8.65)}$ BSC

$\frac{.236}{(5.99)}$ BSC

Top View

$\frac{.154}{(3.90)}$ BSC

$\frac{.007 \pm .003}{(.175 \pm .075)}$

See Detail A

$\frac{.016 \pm .004}{(.410 \pm .100)}$

$\frac{.050}{(1.27)}$ BSC

$\frac{.069}{(1.750)}$ max.

0 · to 8 ·

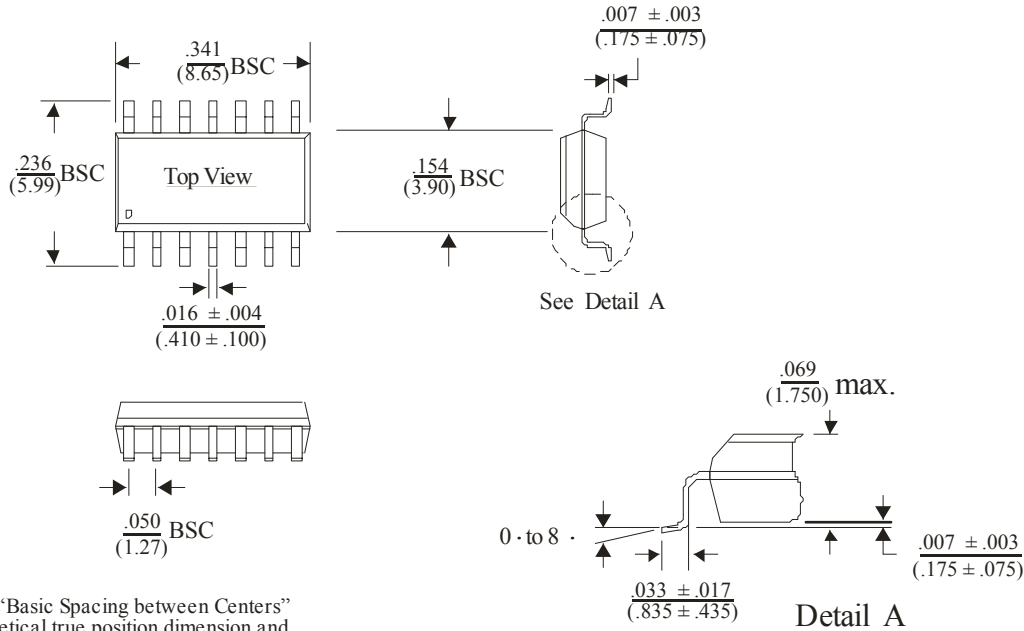$\frac{.033 \pm .017}{(.835 \pm .435)}$

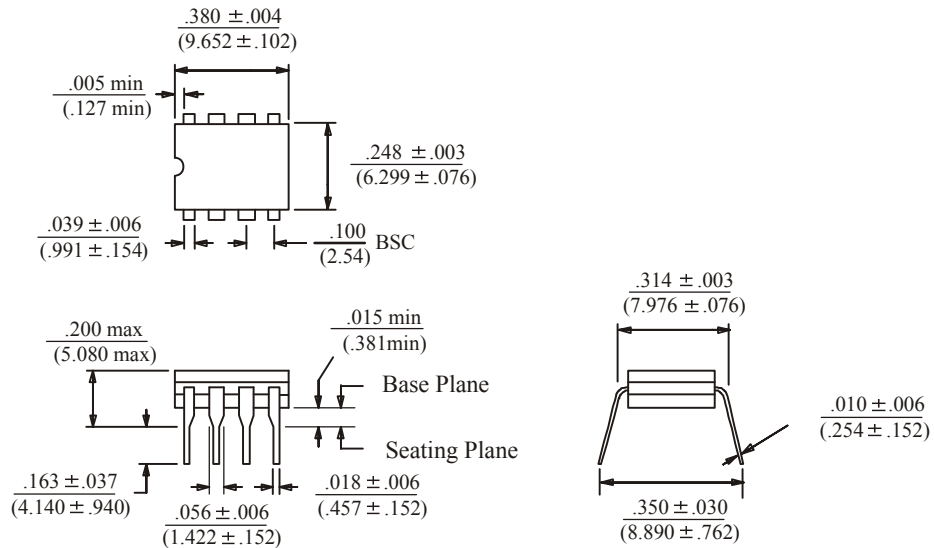$\frac{.007 \pm .003}{(.175 \pm .075)}$

Detail A

BSC = "Basic Spacing between Centers"
is theoretical true position dimension and
has no tolerance. (JEDEC Standard 95)

8-PIN CERDIP

inches (millimeters)

Package Type: 8D

$\frac{.380 \pm .004}{(9.652 \pm .102)}$

$\frac{.005 \min}{(.127 \min)}$

$\frac{.248 \pm .003}{(6.299 \pm .076)}$

$\frac{.039 \pm .006}{(.991 \pm .154)}$

$\frac{.100}{(2.54)}$ BSC

$\frac{.200 \max}{(5.080 \max)}$

$\frac{.015 \min}{(.381 \min)}$

Base Plane

Seating Plane

$\frac{.163 \pm .037}{(4.140 \pm .940)}$

$\frac{.056 \pm .006}{(1.422 \pm .152)}$

$\frac{.018 \pm .006}{(.457 \pm .152)}$

$\frac{.314 \pm .003}{(7.976 \pm .076)}$

$\frac{.010 \pm .006}{(.254 \pm .152)}$

$\frac{.350 \pm .030}{(8.890 \pm .762)}$

BSC = "Basic Spacing between Centers"
is theoretical true position dimension and
has no tolerance. (JEDEC Standard 95)